TALENT Course 6: Theory for exploring nuclear reaction experiments Supplementary handout 1: Monday Week 1 Jeff Tostevin

Two-particle bound and scattering states calculations

Introduction

Codes provided that solve the (non-relativistic) radial Schrödinger equation

$$\left(\frac{d^2}{dr^2} - \frac{\ell(\ell+1)}{r^2} + \frac{2\mu}{\hbar^2} [E_{cm} - V(r)]\right) u_{\ell}(r) = 0 ,$$
(1)

for bound $(E_{cm} < 0)$ and scattering $(E_{cm} > 0)$ solutions for a system of two particles of masses A_1 (projectile) and A_2 (target), and reduced mass μ , interacting via a potential V(r), are bound and scatter. The potential V(r) will, in general, consist of short ranged interactions $V_N(r)$ plus the Coulomb interaction $V_C(r)$ when the projectile (Z_1) and target (Z_2) are charged. For bound states $V_N(r)$ is simply assumed to be a real central interaction with a Woods-Saxon shape. For scattering states $V_N(r)$ will in general be assumed to be an arbitrary complex central interaction based on the usual volume and surface Woods-Saxon shapes, as follows

$$V(r) = V_N(r) + V_C(r) = \left\{ -\frac{V_0}{(1 + e^{X_0})} - i \frac{W_v}{(1 + e^{X_v})} - i \frac{4W_s e^{X_s}}{(1 + e^{X_s})^2} \right\} + V_C(r).$$
 (2)

So, for an attractive (negative) real potential and an absorptive (negative) imaginary potential the strengths V_0 , W_v and W_s are each defined to be positive. In the above equation the factors X_i are

$$X_i = (r - R_i)/a_i , \qquad R_i = r_i A_2^{1/3} ,$$
 (3)

with r_i and a_i the usual radius and diffuseness parameters (typically of order 1.2 and 0.6 fm, respectively). The Coulomb interaction $V_C(r)$ for charged particles is assumed to be that of a uniformly charged sphere with a radius R_C , taken here to be equal to that assigned to the real central interaction $R_C = R_0 = r_0 A_2^{1/3}$, and is then

$$V_C(r) = \frac{Z_1 Z_2 e^2}{r}, \qquad r > R_C \tag{4}$$

$$= \frac{Z_1 Z_2 e^2}{2R_C} \left[3 - \left(\frac{r}{R_c}\right)^2 \right]. \qquad r \le R_C. \tag{5}$$

Spin-orbit interactions are not necessary for the currently required outcomes and the strengths can be set to zero if programs prompt for them for the time being.

Outputs from scatter are the radial wave functions $u_{\ell}(r)$ (see Eq. 14), the phase shifts δ_{ℓ} and the partial wave T- and S-matrices, $T_{\ell}(E_{cm}) = e^{i\delta_{\ell}} \sin \delta_{\ell}$ and $S_{\ell}(E_{cm}) = e^{2i\delta_{\ell}}$. The integrated elastic scattering cross section is

$$\sigma(E_{cm}) = \sum_{\ell=0}^{\infty} \sigma_{\ell}(E_{cm}) = \frac{4\pi}{k^2} \sum_{\ell=0}^{\infty} (2\ell+1) |T_{\ell}(E_{cm})|^2 .$$
 (6)

The contributions from each partial wave ℓ , are

$$\sigma_{\ell}(E_{cm}) = \frac{4\pi}{k^2} (2\ell + 1) |T_{\ell}(E_{cm})|^2 \tag{7}$$

and are also output. For real $V_N(r)$, δ_ℓ is also real and then $|T_\ell(E_{cm})|^2 = \sin^2 \delta_\ell$.

Program bound

This program works in terms of the positive separation energy S_{cm} of the bound particles rather than the negative energy eigenvalue E_{cm} , with $S_{cm} = -E_{cm}$. The program can find either

- (a) the bound states in a specified fixed potential, or
- (b) the potential that will produce a bound state with a particular separation energy.

The program is self documenting, asking for the required input parameters. If used without spin-orbit forces, respond in any way to the spin- and j-value requests and return zero for the spin-orbit potential strength. The real radial wave functions $u_{\ell}(r)$ for the bound states are defined such that

$$\int_0^\infty dr r^2 [u_\ell(r)/r]^2 = \int_0^\infty dr [u_\ell(r)]^2 = 1,$$
 (8)

and thus behave as $r^{\ell+1}$ near the origin. The wave functions are written as $(r, u_{\ell}(r))$ pairs to the file bound.xxx for graphical use and as $u_{\ell}(r)/r$ values to the file bd.xxx for further computation and interface with other codes. The distinguishing trailer xxx is user-specified.

The wave functions are calculated for the range of radii $0 \le r \le 30$ fm.

The number of nodes in the radial wave function starts with n=0 for the lowest energy state of a given ℓ , so the zeroes of the wave function at the origin and at infinity are not counted in the node count.

Program scatter

A specimen data set scatter.one contains the specification of the required inputs.

projectile: mass charge target: mass charge

```
matching radius (fm)
                             (typically 15. fm)
integration step length
                             (typically 0.1 fm)
centre of mass energies:
                              e_{min}
                                         e_max
number of energies:
                              nener
partial waves:
                              1_min
                                      l_{max}
Real Woods-Saxon (volume)
                              V_0
                                    r_0
                                           a_0
Imag Woods-Saxon (volume)
                              W_v
                                    r_v
                                           a_v
Imag Woods-Saxon (surface)
                              W_s
                                    r_s
                                           a_s
```

The user-specified filename trailer of the data set (here one) will then label all output files from this data set, phases.one, etc. and can be used to identify output from different runs.

The suggested matching radius of 15.0 fm, beyond which $V_N(r)$ is assumed to vanish (see Appendix), and integration step of 0.1 fm should be adequate for all of the cases needed here.

The output files produced for a data set scatter.xxx are as follows. The phase shifts, etc. are ordered by the scattering energy for each value of ℓ , with an xmgr recognised separator.

```
phases.xxx phase shifts in degrees (real V_N): Ecm delta potent.xxx the potential V_N(r): r Re.V_N Im.V_N V_C smatrix.xxx partial wave S-matrix elements: ell Re.S Im.S |S| tmatrix.xxx partial wave T-matrix elements: ell Re.T Im.T wavefun.xxx radial wave functions: r Re.u Im.u sigmas.xxx partial cross sections of Eq.(7) Ecm sigma (fm**2)
```

The routines scatter and bound are intended to provide a foundation from which to understand the behaviours of outputs from a set for potential scattering and bound states problems. The intention is to understand those aspects of scattering that guide intuition and that are needed as input to larger-scale reaction calculations. We can use these programs later to test approximate scattering theories by comparison with the exact results and also to examine and fine-tune input we put into reaction codes and so test individual inputs.

Appendix A: Outline of solution

(1) The codes calculate numerically the solutions of the radial differential equations in the presence of the potentials V(r), for each relative orbital angular momentum (or partial wave) ℓ ,

$$\left(\frac{d^2}{dr^2} - \frac{\ell(\ell+1)}{r^2} + \frac{2\mu}{\hbar^2} [E_{cm} - V(r)]\right) u_{\ell}(r) = 0$$
(9)

- (2) The required (physical) solutions are regular (i.e. $u_{\ell}(r) = 0$) at the origin. Here, μ is the projectile-target reduced mass.
- (3) Outside of the range of the nuclear (Woods Saxon) interactions, where $V(r) \to V_C(r)$, the radial equation can be written

$$\left(\frac{d^2}{dr^2} - \frac{\ell(\ell+1)}{r^2} - \frac{2\eta k}{r} + k^2\right) u_{\ell}(r) = 0$$
(10)

where η is the Sommerfeld (Coulomb) parameter and k is the wavenumber, $k^2 = 2\mu E_{cm}/\hbar^2$.

(4) The regular, $F_{\ell}(\eta, kr)$, and irregular, $G_{\ell}(\eta, kr)$, (Coulomb function) solutions of this equation are well known and standard functions.

To outline the solution, consider the scattering of uncharged particles, for which $\eta = 0$. Numerical integration is performed away from the origin using the Numerov algorithm (outlined in the following section) using an integration step length h (to be specified).

The numerical solution is then matched to the required physical solution at a radius R_{match} (to be specified), outside of the ranges R of the Woods Saxon potentials, i.e. for which $V(r) = V_N(r) = 0$, $r \ge R$. For these radii

$$u_{\ell}(r) = A_{\ell}F_{\ell}(0,kr) + B_{\ell}G_{\ell}(0,kr) , \quad (r > R) ,$$
 (11)

$$\rightarrow C_{\ell} \sin(kr - \ell\pi/2 + \delta_{\ell}) , \quad (r \rightarrow \infty) , \qquad (12)$$

where $F_{\ell}(0, kr)$ and $G_{\ell}(0, kr)$ are the solutions of Eq. 10 for $\eta = 0$ – the free particle (no potential) radial equation.

These have very simple forms for small ℓ ,

$$F_0(0,kr) = \sin(kr)$$
, $G_0(0,kr) = \cos(kr)$,
 $F_1(0,kr) = \frac{\sin(kr)}{kr} - \cos(kr)$, $G_1(0,kr) = \frac{\cos(kr)}{kr} + \sin(kr)$,

and for other ℓ satisfy the recurrence formula

$$F_{\ell+1}(0,kr) = \frac{2\ell+1}{kr} F_{\ell}(0,kr) - F_{\ell-1}(0,kr) ,$$

and similarly for the G_{ℓ} . They have the asymptotic forms

$$F_{\ell}(0,kr) \rightarrow \sin(kr - \ell\pi/2)$$
,
 $G_{\ell}(0,kr) \rightarrow \cos(kr - \ell\pi/2)$.

The matching to the physical solution at radii r > R is carried out at two radii r_1 and r_2 . That is the simultaneous equations

$$u_{\ell}(r_1) = A_{\ell}F_{\ell}(0, kr_1) + B_{\ell}G_{\ell}(0, kr_1) ,$$

$$u_{\ell}(r_2) = A_{\ell}F_{\ell}(0, kr_2) + B_{\ell}G_{\ell}(0, kr_2) ,$$

are solved for A_{ℓ} , B_{ℓ} .

These constants of solution A_{ℓ} and B_{ℓ} determine the scattering phase shift, according to $A_{\ell} = C_{\ell} \cos \delta_{\ell}$, $B_{\ell} = C_{\ell} \sin \delta_{\ell}$, with $C_{\ell} = \sqrt{A_{\ell}^2 + B_{\ell}^2}$, and hence $\delta_{\ell} = \arctan(B_{\ell}/A_{\ell})$. The partial wave T- and S-matrix elements $T_{\ell}(E_{cm})$ and $S_{\ell}(E_{cm})$ are

$$T_{\ell}(E_{cm}) = e^{i\delta_{\ell}} \sin \delta_{\ell}, \qquad S_{\ell}(E_{cm}) = e^{2i\delta_{\ell}}.$$
 (13)

The radial wave function defined by Eq. 12 is useful as it real for the case that V(r) is real. The wave function printed from scatter.f is defined such that

$$u_{\ell}(r) \to \cos \delta_{\ell} F_{\ell}(\eta, kr) + \sin \delta_{\ell} G_{\ell}(\eta, kr) , \quad (r > R) .$$
 (14)

Appendix B: Numerical outline

The Numerov algorithm for the solution of a homogeneous second order ordinary differential equation of the general form

$$u''(r) = \mathcal{K}(r)u(r) ,$$

using a constant step/interval h, is based on the relationship

$$\left[1 - \frac{h^2}{12}\mathcal{K}(r+h)\right]u(r+h) = \left[2 + \frac{5h^2}{6}\mathcal{K}(r)\right]u(r) - \left[1 - \frac{h^2}{12}\mathcal{K}(r-h)\right]u(r-h) .$$

The error involved is of order h^6 and is thus rather accurate for reasonably small h. In the context of the radial Schrödinger equation we must associate

$$\mathcal{K}(r) \equiv \mathcal{K}_{\ell}(r) = \frac{\ell(\ell+1)}{r^2} + \frac{2\mu}{\hbar^2} [V(r) - E_{cm}] .$$

The solution is computed iteratively, from a knowledge of the behaviour of the regular solution at r=0 and $r=h, \propto (kr)^{\ell+1}$. Inspection will show that some care needed in specifying these starting conditions for the case that $\ell=1$. This special case is taken care of in the program scatter.f.

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